# **Image Analysis**

### **Routines for Alignment, Inspection, and Drop Analysis**

### **Product Description**

Custom image analysis routines are enabled in the JetServer<sup>™</sup> and Jetlab<sup>®</sup> control programs by adding a runtime version of the Aphelion image analysis software to a subsystem using a Jetdrive III and video capture or to a Jetlab<sup>®</sup> Printing Platform. These routines allow for:

- improved and additional calibration / alignment options;
- measurement of droplet size, velocity and trajectory polar angle from vertical direction; and
- surveying of printed spot patterns (Jetlab<sup>®</sup> Printing Platforms).

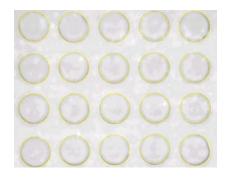


#### **Standard Features**

- Generation and display of scales over both vertical and horizontal camera images, enabling rapid, accurate manual measurements.
- Multiple selection algorithms and tuning tools for automatic edge detection.
- Automated measurement of drop parameters: diameter, velocity, trajectory angle (one plane).
- Automated measurement and location of fiducials and printed features. Used for alignment of drops to substrate features and rotation correction.

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### **Available Options**

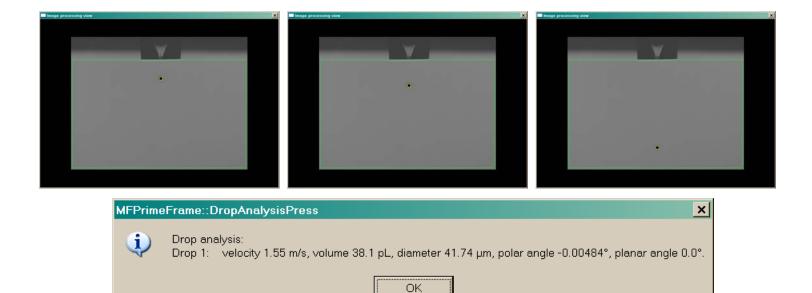
 Aphelion developer version for standalone work on image processing/analysis.

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#### **Ordering Information**

CT-VC-02	Sensoray video capture board, USB.
CT-VC-01	Sensoray video capture board, PCI.
CT-VC-core	Image analysis software and custom
	image analysis routines.





#### Specifications\*

Jetlab <sup>®</sup> II (observation and substrate)	2.1 µm / pixel – max zoom 21 µm / pixel – min zoom	
Jetlab <sup>®</sup> 4 (substrate)	4 µm / pixel	
Jetlab <sup>®</sup> 4 (observation – angled)	6.5 μm / pixel	
Jetlab <sup>®</sup> 4xl-A (observation – horizontal)	6.5 μm / pixel	
* note: for standard Jetlab <sup>®</sup> II and Jetlab <sup>®</sup> 4 optics and camera		



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